# JAN-901B ECDIS



– introducing a new high performance ECDIS, integrating the latest technologies and innovative features

23-inch high visibility display Simultaneous real-time radar & AIS overlay Advanced route planning Multiple and wide screen viewing High-speed graphic processor



### JAN-901B – performance features

#### **Unique features**

• The JAN-901B is a newly developed multi-functional ECDIS. It is ergonomically designed to enhance the working environment and man/machine interfaces, providing continuous position and navigational safety information.

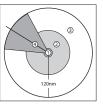
#### Radar overlay

The JRC JAN-901B offers practical radar usage with ECDIS, more than just overlaying a rough radar image. The radar mage has a high resolution when interfaced with JRC radars. The radar image does not hide the priority objects of vector charts, but overlays them on the radar image. At the same time, brilliance and clutter controls of the radar images continues to be operable.

### AIS targe<mark>ts</mark>

The AIS is an important key device used to indicate AIS target symbol and information on the ECDIS. These targets are very useful, as it provides the maneuvering conditions of other ships at a glance, allowing for safe and effective navigation. The name of

Also, it is easy to active, deactivate and switch between AIS target symbols. This simply can be done with an integrated AIS filter, prioritising the targets within a dedicated area. the vessels, and bearing, range, speed, length, heading and much more AIS target specifics from other ships are received and displayed. The AIS symbols are continuously displayed on-screen without the influence of the radar characteristics. The AIS targets are never shielded by ground, rain or cloud reflections, nor are they eliminated by adjustments of anti-sea or anti-rain clutter.



1. vessels' position

2. ring area

3. sector area

4. heading area

### Multi-view

01B ECDIS - a newly developed multi-fu

Multiple and wide screen viewing is possible with the new JAN-901B. You can divide the chart screen into two sections, in which the same or different charts can be displayed, in a mixture of ways. In this field of view, it provides a 'look-ahead' capability, especially useful in coastal areas. With the wide screen view function, an additional screen in the display area, showing a segment of the chart, allows viewing at a glance.

### JAN-901B – developed for maximum ease of use

### Flexible black box configuration

The ECDIS system is available in stand alone and desktop versions to suit your type of vessel. In the desktop version, the processor unit is the heart of the JAN-901B, allowing for flexible installation approach in confined spaces.

### User interface

With its simplified menu structure, the new JAN-901B shares the same insightful user interface as found in JRC's new radar series. The consistent visual appeal and intuitive usage is of great importance on the vessels bridge, especially being a working and living environment for thousands of vessels' officers on a day to day base.





ecdis

### Conning and external sensors

You can easily connect a wide range of navigation equipment to acquire more information. The ECDIS will display exactly the info you need in a clear, uncluttered format, reducing the risk of accidents. This results in a more relaxing and secure operation. Even equipment from different manufacturers can be incorporated.

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### More powerful than ever

The JAN-901B incorporates two Tornado<sup>™</sup> processors, which are exclusively developed and designed by JRC, bringing a new level of performance and reliability to ECDIS operation. The new Tornado<sup>™</sup> processors, which equal the power of eight conventional processors, allow radar overlay processing within a few milliseconds before displayed. This generates a smooth and fast image update. The advanced system architecture, make the JAN-901B series probably the most sophisticated ECDIS available today.

### CCRP

As set by IMO regulations, a Consistent Common Reference Point (CCRP) is a location on own ship, to which all horizontal measurements, such as target range, bearing, relative course/ speed, closest point of approach, or time to closest point of approach are referenced.

Where multiple antennas are installed, different position offsets for each antenna in the radar system should be applied with respect to the CCRP. If you switch between scanners (up to 8 possible - option), the information displayed is generated, which allow for consistency and uniform output.



nctional system

Some items could strike you on the vessel, a slippery deck or unexpected movement of the vessel are situations in which a person may possibly fall of the vessel. The JAN-901B integrates a single-press Man OverBoard (MOB) operation. Instantly, a dedicated symbol arises on the screen, providing a range detailed info such as positioning, bearing, range and time till arriving at MOB. This emergency system enables immediate and accurate search and rescue efforts.

## JAN-901B – easy user interface





## JAN-901B – routing flexibility

### Advanced route planning

The advanced nature of JRC's new ECDIS system allows route planning in different ways. Either plan your route by using the table editor, while displaying current waypoint or graphically draw your next waypoint on the chart. Editing the route is just as simple as inserting. Dedicated menus are readily available to assist the mariner in effective route planning. Not only can you save the routes, but import favourite or commonly used files, even from previously ECDIS models, using industry-standard CSV format.

Route planning with table editor while displaying waypoints During the voyage, you can add an alternative route, which can be displayed simultaneously. You can move, insert, add and delete waypoints instantly and easily exchange the alternative route with route in progress, at your own convenience.

### Editing the user maps

The JAN-901B provides a rich suite of objects which you single-handedly can enter, move, insert and add on user maps. The objects consist of symbols, lines, areas and texts. From buoys



to buildings and harbour to seabed signals, JRC's new ECDIS has a total of over 40 categories and 30 sub-categories, which include more than 250 graphics readily available for endless possibilities.

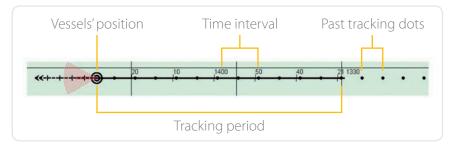
The user map is linked to the chart, and even if there are multiple user maps, you can easily select or merge.

#### A few examples



### Track and time label

The vessels' primary position is saved with a minimum interval of three seconds, and the tracking period on the chart is displayed up to 24 hours. Conveniently mark your past track, choosing out of seven colours, eight tracking periods, ten time intervals and eight nautical mile presets.





### What's standard in the box?

With our new JAN-901B ECDIS series you have four system choices to select from. All are available in desktop or stand alone version, making it more than ideal for your preferred installation approach.

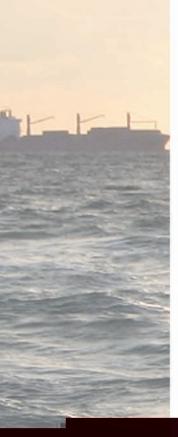
#### JAN-901B stand alone-desktop

| Versions                               |  | SOO•FOC  | SOR•FOR                           | SCR•F(                   | R SCO-FCO         |  |
|--|--|----------|-----------------------------------|--------------------------|-------------------|--|
| Stand alone unit                       |  | 0        | 0                                 | 0                        | 0                 |  |
|  |  |          |                                   |                          |                   |  |
| Keyboard                               |  |          |                                   |                          |                   |  |
|  |  |          |                                   |                          |                   |  |
| ECDIS software                         |  | 0        | 0                                 | 0                        | 0                 |  |
| Radar overlay                          |  |          | 0                                 | 0                        |                   |  |
| Analogue interface                     |  |          |                                   | 0                        | 0                 |  |
| Conning software                       |  |          |                                   | 0                        | 0                 |  |
| Accessories                            |  | 0        | 0                                 | 0                        | 0                 |  |
| Installation kit                       |  | 0        | 0                                 | 0                        | 0                 |  |
| Operation manual                       |  | 0        | 0                                 | 0                        | 0                 |  |
| <b>SOO</b> ECDIS <b>SOR</b> ECDIS/rada |  | NS/radar | SCR ECDIS/rada                    | <b>SCO</b> ECDIS/conning |                   |  |
| FOO ECDIS FOR ECDIS                    |  | IS/radar | ar <b>FCR</b> ECDIS/radar/conning |                          | FCO ECDIS/conning |  |

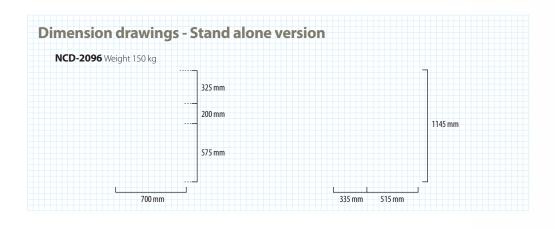
#### Version comparison

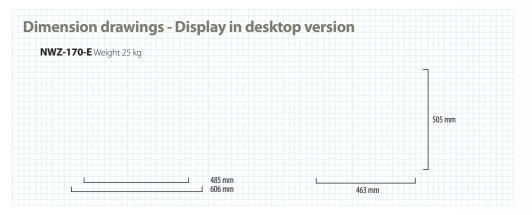
Below a specification comparison between the different versions available.

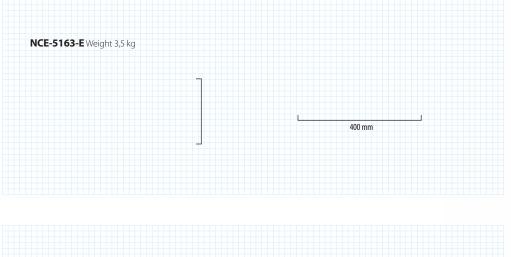
| Versions                          | 500•F00        | SOR•FOR        | SCR•FCR        | SCO•FCO        |
|-----------------------------------|----------------|----------------|----------------|----------------|
| Console design                    |                |                |                |                |
| Tilting display                   | 0              | 0              | 0              | 0              |
| Hardware design                   |                |                |                |                |
| Vibration absorber                | 0              | 0              | 0              | 0              |
| CD/DVD ROM drive                  | 0              | 0              | 0              | 0              |
| Dual hard disk                    | 0              | 0              | 0              | 0              |
| Silicon disk                      | 0              | 0              | 0              | 0              |
| Battery for auto shut down        | 0              | 0              | 0              | 0              |
| Network adapter (LAN)             | 0              | 0              | 0              | 0              |
| Radar interface                   |                |                |                |                |
| Radar video input                 |                | 0              | 0              |                |
| Serial interface                  |                |                |                |                |
| Gyro                              | 0              | 0              | 0              | 0              |
| Doppler log (VBW)                 | 0              | 0              | 0              | 0              |
| GPS (gga, vtg, zda, dtm, gns)     | 0              | 0              | 0              | 0              |
| NAVTEX (JRC format)               | 0              | 0              | 0              | 0              |
| Echo sounder (DPT)                | 0              | 0              | 0              | 0              |
| ARPA (TTM)                        | 0              | 0              | 0              | 0              |
| AIS (VDM)                         | 0              | 0              | 0              | 0              |
| Auto pilot (HTC, HTD)             | 0              | 0              | 0              | 0              |
| Anemometer (MWV)                  |                |                | 0              | 0              |
| Atmospheric pressure (MTA, XDR)   |                |                | 0              | 0              |
| Air temperature (MMB, XDR)        |                |                | 0              | 0              |
| Water temperature (MTW, XDR)      |                |                | 0              | 0              |
| Humidity (MHU, XDR)               |                |                | 0              | 0              |
| Rudder angle (RSA)                |                |                | 0              | 0              |
| Rate of turn (ROT)                |                |                | 0              | 0              |
| Engine RPM (RPM, PJM07)           |                |                | 0              | 0              |
| Other serial input (option)       |                |                | 0              | 0              |
| Analogue interface                |                |                |                |                |
| Gyro (synchro or step)            | O <sup>1</sup> | O <sup>1</sup> | 01             | O <sup>1</sup> |
| Log (200P/NM)                     | O <sup>1</sup> | O <sup>1</sup> | O <sup>1</sup> | O <sup>1</sup> |
| Anemometer (synchro or 4-20mmA)   |                |                | 0              | 0              |
| Rudder angle (synchro or 4-20mmA) |                |                | 0              | 0              |
| Bow thruster pitch (4-20mmA)      |                |                | 0              | 0              |
| Bow thruster RPM (4-20mmA)        |                |                | 0              | 0              |
| Stern thruster pitch (4-20mmA)    |                |                | 0              | 0              |
| Stern thruster RPM (4-20mmA)      |                |                | 0              | 0              |
| Propeller pitch (4-20mmA)         |                |                | 0              | 0              |
| Propeller RPM (4-20mmA)           |                |                | 0              | 0              |
| Dry contact                       |                |                |                |                |
| Original (6 points)               | 0              | 0              | 0              | 0              |
| Option (6 points)                 | O <sup>2</sup> | O <sup>2</sup> | 0              | 0              |



### **JAN-901B** - dimensions and weights







| 575 mm | NDC-1444 Weight 85 kg |           |  |  |
|--------|-----------------------|-----------|--|--|
|        |                       |           |  |  |
|        |                       | 676 mm    |  |  |
|        |                       | 373 11111 |  |  |
|        |                       |           |  |  |



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## JAN-901B – specifications

| Model                                       |                                    | JAN-901B  |  |  |  |
|---|------------------------------------|---|--|--|--|
| IMO compliant                               |                                    | $\checkmark$  |  |  |  |
| General                                     |                                    |   |  |  |  |
| 0   | S                                  | Windows XP embedded   |  |  |  |
| Po  | ower supply                        | 100-115V to 200-230V AC ±10%, 60/50 Hz ±5%  |  |  |  |
|   | ower consumption                   | 300 VA or less  |  |  |  |
| Display                                     | · .                                |   |  |  |  |
|   | ze                                 | 23-inch colour LCD display  |  |  |  |
| Re  | esolution                          | 1600 by 1200 pixels (UXGA)  |  |  |  |
| EE  |                                    | 2 (EBL1, EBL2)  |  |  |  |
| VE  | RM                                 | 2 (VRM1, VRM2)  |  |  |  |
|   | earing indication                  | north-up, course-up (simultaneously in multi view)                                      |  |  |  |
|   | resentation mode                   | true, relative, free motion   |  |  |  |
|   | lulti display areas                | 2 (longitudinal, transverse, picture in picture)  |  |  |  |
|   | cale                               | 1:1.000 up to 1:75.000.000  |  |  |  |
|   | ange                               | 0.125 - 120 nm  |  |  |  |
| Route planning                              |                                    | 0.125 120100  |  |  |  |
|   | iput                               | graphical or numerical  |  |  |  |
|   |                                    | grounding, obstruction, dangerous areas   |  |  |  |
|   | afety check<br>nport/export format | CSV   |  |  |  |
|   |                                    |   |  |  |  |
|   | mit check                          | 1) TCS only: turn radius, route width   |  |  |  |
| Monitoring                                  |                                    | Over example a state of an end to a d   |  |  |  |
|   | otting                             | Own vessel position and track   |  |  |  |
|   | RPA tracking                       | 200   |  |  |  |
|   | IS tracking                        | 300 (sleeping + activated)  |  |  |  |
|   | IS class                           | class A + class B   |  |  |  |
|   | IS/ARPA alarm                      | СРА/ТСРА  |  |  |  |
| Chart managen                               |                                    |   |  |  |  |
|   | pdating                            | semi-auto, manual (available via ChartCo)   |  |  |  |
|   | ata correction                     | available   |  |  |  |
| Conning display                             |                                    |   |  |  |  |
| Na  | avigation screen                   | date/time, speed, route planning info, engine data, rudder data, weather/sea conditions |  |  |  |
| Ha  | arbour/docking screen              | speed, docking/sway speed, thruster data  |  |  |  |
| AI  | larm management screen             | complete and detailed alarm status, acknowledge   |  |  |  |
| Interfaces                                  |                                    |   |  |  |  |
| G   | yro input                          | 2) IEC61162-2 or synchro/step   |  |  |  |
| Lo  | og input                           | 2) IEC61162-1 or 200 pulse  |  |  |  |
| Re  | emote maintenance                  | possible  |  |  |  |
| Co  | opying route                       | FD, USB   |  |  |  |
| N   | etwork                             | LAN (10/100 Mbps)   |  |  |  |
| Optional items                              |                                    |   |  |  |  |
| HUB (for multip                             | le radars/RPS connector)           | 7EZNA4008   |  |  |  |
| Junction box route HUB                      |                                    | CQD-10  |  |  |  |
| Gyro interface unit                         |                                    | MPXP34120   |  |  |  |
| Mini keyboard                               |                                    | 5EZKT00022  |  |  |  |
| Route planning                              | system (RPS)                       | JAN-1186-19   |  |  |  |
| Display cover                               | .,.,                               | MPXP33089   |  |  |  |
| Display cover<br>Display hood               |                                    | MPOL30345A  |  |  |  |
| 1) IAN-901B is compliant with TCS specifies |                                    |   |  |  |  |

1) JAN-901B is compliant with TCS, specified in IEC62065 - category C 2) Gyro I/F unit is needed All specified in IEC62065 - category C 2) Gyro I/F unit is needed

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All specifications are subject to change without notification.

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